

Chapter-6

# Electromagnetic Induction



**CBSE CLASS XII NOTES**

**Dr. SIMIL RAHMAN**

*MSc, Ph.D, B.Ed,*

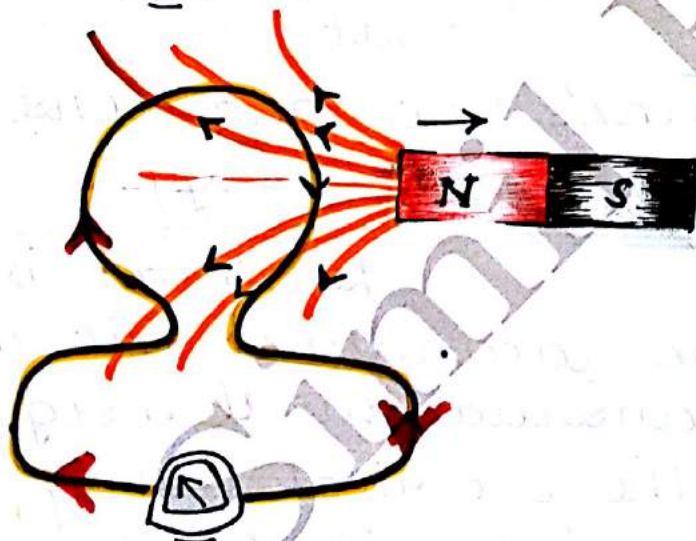
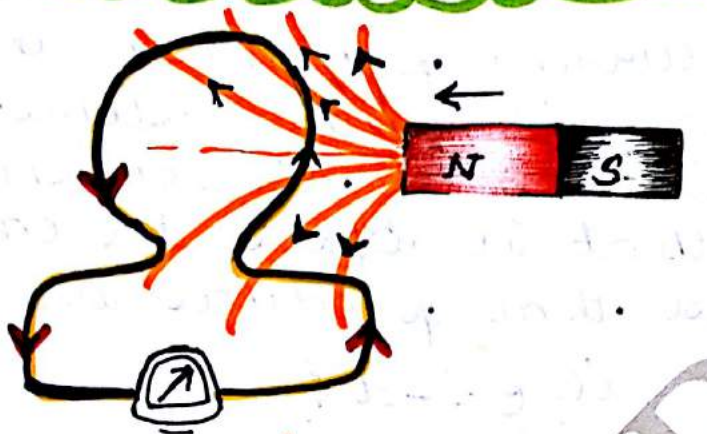
*D.E.E.I Engineering, SET, MA*

*MES DOHA QATAR*

# Electromagnetic Induction

Whenever magnetic flux linked with a conductor changes an emf is induced in the conductor.

## Faradays experiment



When a bar magnet is moved towards the loop of wire, the galvanometer shows deflection.

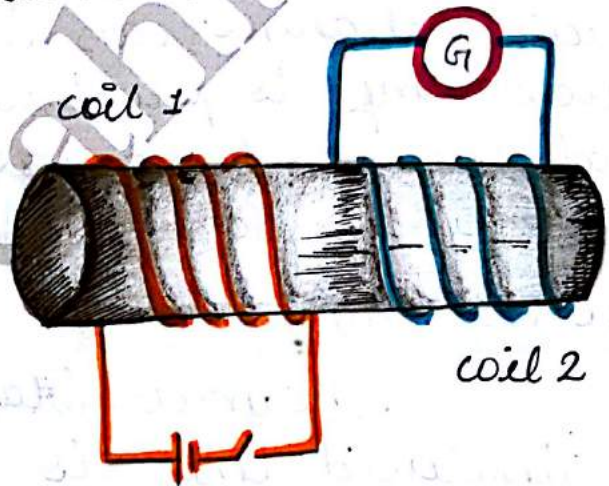
\* If the magnet is moved towards the coil, galvanometer shows deflection in one

direction

\* If the magnet is moved away from the coil deflection is in opposite direction.

\* If the magnet is kept stationary no deflection.

\* If relative motion b/w magnet and coil increases more current will be induced.



Two wires are wound independently on a cylindrical support

\* Press key K in the coil 1. Galvanometer in coil 2 shows deflection in one direction.

\* Release key K, G shows deflection in opposite direction.

\* If continuously pressed (K); no deflection in G



as no change in magnetic flux.

conclusion: emf is induced when there is a change of magnetic flux.

## Faraday's law of EMI

### First law

whenever magnetic flux linked with a coil changes, an induced emf is produced and last as long as the change occurs.

### second law

The magnitude of induced emf is directly proportional to the rate of change of magnetic flux in the coil.

i.e.,  $\text{emf} = \text{rate of change of magnetic flux}$

$$e = -\frac{d\phi}{dt}$$

-ve sign indicates the nature of emf  $e$  such that it opposes the cause which produces it.

uses it.

for 'n' turns

$$e = -N \frac{d\phi}{dt}$$

\* This is also known as Faraday - Lenz's rule

## Lenz's law.

The induced current produced in a coil always flows in such a direction that it opposes the cause that produces it.

i.e.,  $e = -\frac{d\phi}{dt}$

Lenz's law and conservation of energy.

Lenz's law is in accordance with the conservation of energy. The electrical energy produced in the form of induced 'emf' is at the expense of mechanical energy.

mechanical work (motion of magnet/coil)  $\rightarrow$  Electrical energy



## methods of producing induced emf.

$$\phi = BA \cos \theta$$

$$e = -\frac{d\phi}{dt} = -\frac{d}{dt}(BA \cos \theta)$$

emf can be induced by changing

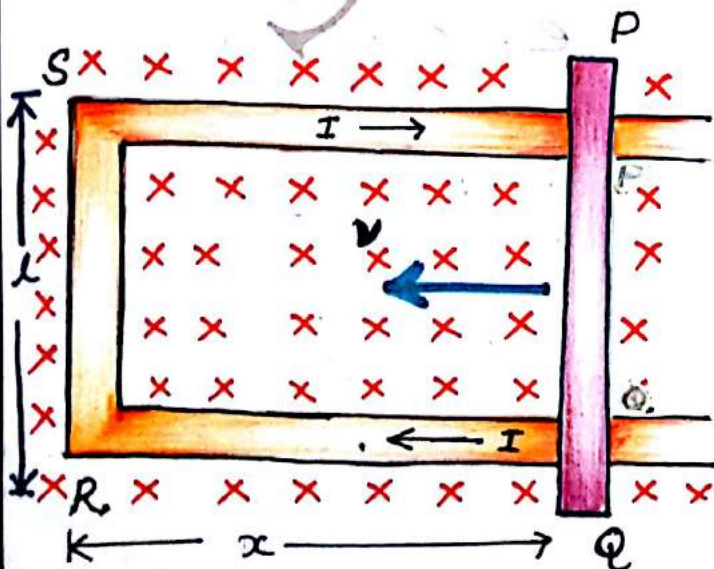
- (i) changing 'B'
- (ii) changing 'A'
- (iii) changing ' $\theta$ '.

## methods of inducing emf by changing B.

- (i) Relative motion between a magnet and a coil.
- (ii) switching 'on' and 'off' of the neighbouring circuit.
- (iii) Relative motion between two coils.

## Motional Emf

[Inducing emf by changing the area]



\* Emf induced across the ends of a conductor due to its motion in a magnetic field is called **motional emf.**

consider a conductor PQ of length 'l' free to move on U-shaped conducting rails. in a  $\perp$  to B.

\* loop PQRS  $\perp$  to B.

\* PQ moves with uniform velocity v.

\* Area of the loop associated with  $\phi$  changes.

\*  $\phi \downarrow$  hence emf is set up across the ends of conductor PQ because of which an induced current flows in the circuit along the path PQRS.

$$\phi = BA \cos \theta$$

$$\theta = 0^\circ$$

$$\phi = BA = Blx$$

$$e = -\frac{d\phi}{dt} = -\frac{d}{dt}(Blx)$$

$$A = lx$$

$$= -Bl \frac{dx}{dt}$$

$$v = \frac{dx}{dt}$$

x reduces with time

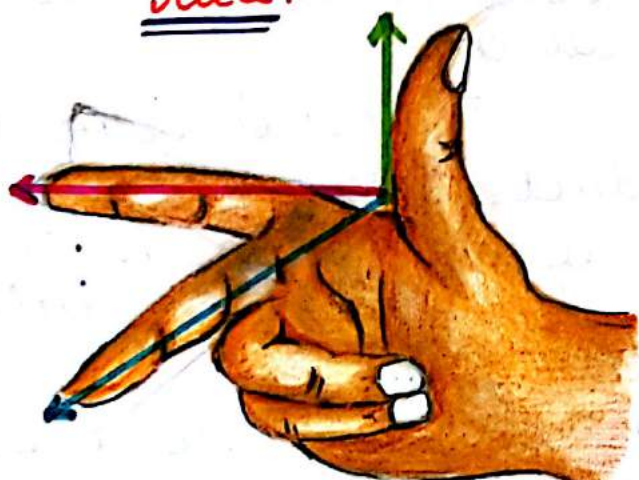
$$\therefore v = -dx/dt$$



$$e = Blv$$

since  $v = \frac{dx}{dt}$

### Fleming's Right hand rule.



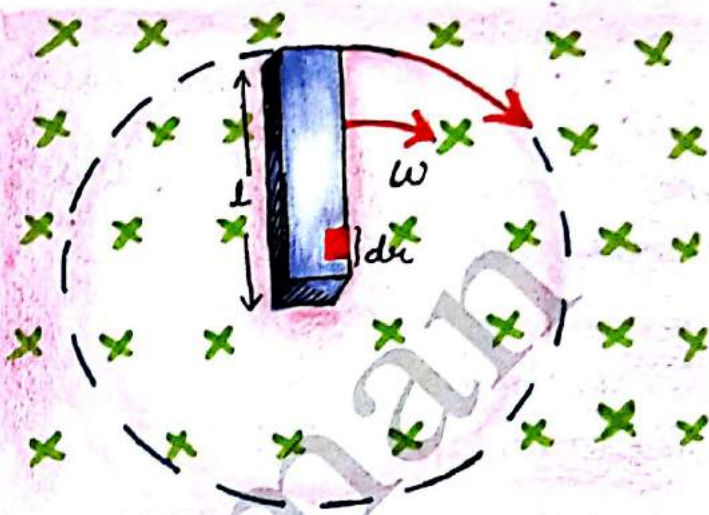
Smul

If we stretch the thumb and first two fingers of our right hand in mutually  $\perp$  directions & if forefinger points in the direction of the magnetic field, thumb in the direction of motion of the conductor, the central finger points in the direction of current induced in the conductor.

Inducing emf in a rotating rod placed in a  $\perp$  Magnetic field.

consider a conducting rod OA of length 'l' rotating

with uniform angular velocity ' $\omega$ ' in  $\perp$  B.



motional emf  $e = Blv$ .

emf due to small element  $dx$

$$de = B dx v$$

$$v = r\omega$$

$$\therefore de = B dx r\omega$$

$$de = B r \omega dx$$

total emf induced b/w ends of rod

$$\int de = \int_0^l B r \omega dx$$

$$e = B \omega \int_0^l r dx$$

$$e = B \omega \left[ \frac{r^2}{2} \right]_0^l$$

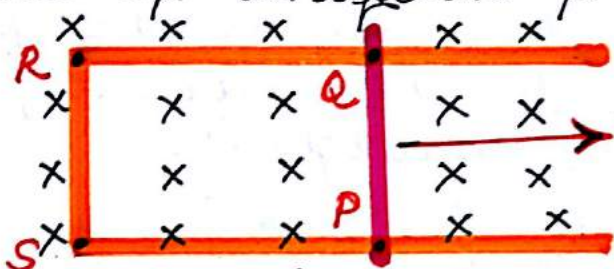
$$e = B \omega \frac{l^2}{2}$$

$$e = \frac{1}{2} B l^2 \omega$$



$$S.T \quad P = \frac{B^2 l^2 v}{R}$$

when a rectangular loop is pulled out of uniform  $B$



mechanical energy.  
power delivered

$$P = F \cdot v$$

$$P = B I l \sin \theta \cdot v$$

$$\theta = 90^\circ$$

$$P = B I l v$$

$$P = B \left( \frac{e}{R} \right) l v$$

$$P = B \left( \frac{B l v}{R} \right) l v$$

$$P = \frac{B^2 l^2 v^2}{R} \quad \text{--- (1)}$$

Electrical energy.

$$P = I^2 R$$

$$P = \left( \frac{e}{R} \right)^2 R$$

$$= \left( \frac{B l v}{R} \right)^2 R$$

$$P = \frac{B^2 l^2 v^2}{R} \quad \text{--- (2)}$$

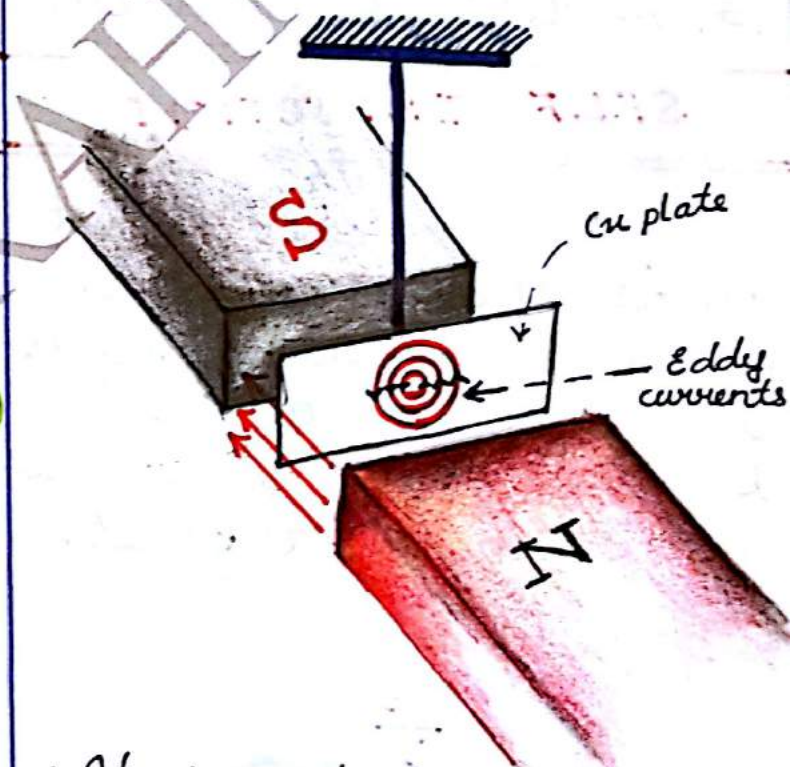
$$(1) = (2)$$

i.e., mechanical energy is

equal to electrical energy is conserved. (3)

## EDDY CURRENTS

Eddy currents are the currents induced in a solid metallic mass when the magnetic flux through them changes.



- \* It produces heat energy
- \* It circulates inside the body.

### Minimising eddy current

- \* By increasing resistance of metal.
- \* By using lamination



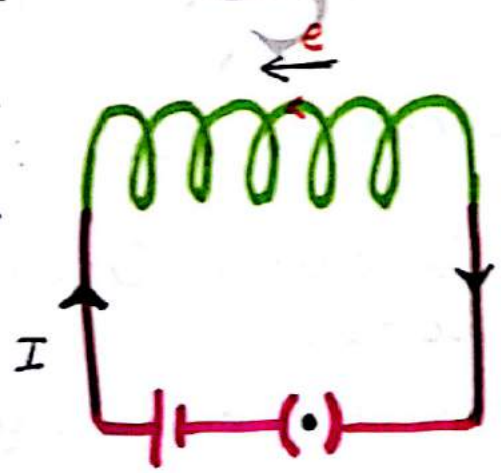
of metals (eg, transformer)

### Application of eddy current.

- (1) Electromagnetic damping
- (2) Induction furnace.
- (3) Electric brakes (magnetic braking in trains)
- (4) speedometers.
- (5) Induction motor.

## SELF INDUCTION

Self Induction is the phenomenon of production of induced emf in a coil by changing the current passing through it.



### Coefficient of self-induction.

The magnetic flux linked with the coil at any instant is directly proportional to the current passing through it.

$$\text{i.e., } \phi \propto I$$

$$\phi = LI$$

where 'L' is the coefficient of self induction [self inductance]

$$L = \frac{\phi}{I}$$

$$L = \phi \text{ when } I = 1 \text{ A}$$

i.e., self inductance of a coil is numerically equal to the magnetic flux linked with the coil when a unit current flows through it. The induced emf

$$e = -\frac{d\phi}{dt}$$

$$e = -\frac{d}{dt}(LI)$$

$$e = -L \frac{dI}{dt}$$

L → is called self inductance.

$$L = \frac{-e}{dI/dt}$$

$$\text{if } \frac{dI}{dt} = \frac{1 \text{ A}}{1 \text{ s}}$$



$$L = -e$$

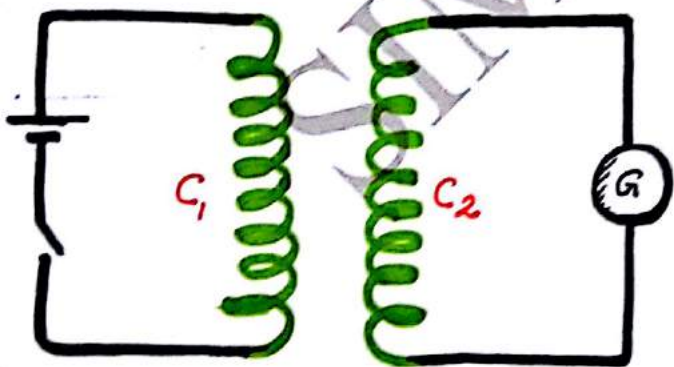
self inductance is equal to emf induced in a coil when current changes at the rate of 1 A/s in the same coil.

\* S.I unit of self Inductance is henry (H)

Define one henry?

self Inductance of a coil is 1 henry when current changes at the rate of 1 A/s through the coil induces an emf of 1V in the coil.

## MUTUAL INDUCTION



The phenomenon by which opposing induced emf is

produced in a coil (4) when there is change in the current or magnetic flux link the neighbouring coil is called mutual Induction.

co-efficient of Mutual Induction [Mutual Inductance]

The flux linked with the secondary coil is directly proportional to the current flowing through the primary coil.

$$\phi \propto I$$

$$\phi = MI$$

M - is the co-efficient of mutual Induction or mutual Inductance.

$$\therefore M = \frac{\phi}{I} \quad \text{or} \quad M = \frac{\phi}{I} \quad \text{when } I = 1 \text{ A}$$

\* mutual Inductance of a pair of coils is equal to the magnetic flux linked with one of the coil when a unit current passes through the coil.



the Induced emf

$$e = -\frac{d\phi}{dt}$$

$$e = -\frac{d}{dt}(MI)$$

$$e = -M \frac{dI}{dt} \quad M = \frac{-e}{dI/dt}$$

$$e = -M \quad \text{if} \quad \frac{dI}{dt} = 1 \text{ A/s}$$

Mutual Inductance is equal to induced emf in a coil when current changes at the rate of 1 A/s in the other coil.

SI unit is H (henry)

Define 1 henry

mutual inductance of a coil is 1 henry when current changes at the rate of 1 A/s through one coil induces an emf of 1 V in the other coil.

### SELF INDUCTANCE OF A LONG SOLENOID.

consider a solenoid of length  $l$ . let 'n' be the no of turns per unit length

$\therefore$  Total no of turns in the solenoid =  $n l$

we have  $\phi = BA \dots (1)$

but  $B = \mu_0 n I \dots (2)$

for 'nl' turns, the total flux

$$\phi = (\mu_0 n I) A (n l)$$

$$\phi = \mu_0 n^2 l A I$$

but  $\phi = LI$

$$LI = \mu_0 n^2 l A I$$

$$L = \mu_0 n^2 l A$$

or

$$L = \frac{\mu_0 N^2 A}{l}$$

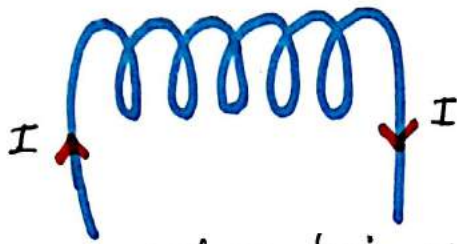
since  $n = \frac{N}{l}$

If the core is of any other material

$$L = \mu_0 \mu_r n^2 l A$$



## Energy stored in an Inductor



when ' $I$ ' flows through solenoid emf is induced which opposes the cause.

$$e = -L \frac{dI}{dt}$$

work must be done against this emf.

$$W = Vq$$

$$dW = e dq$$

$$dW = L \frac{dI}{dt} dq$$

$$dW = L I dI$$

$$\int dW = L \int I dI$$

$$W = L \int_0^I I dI$$

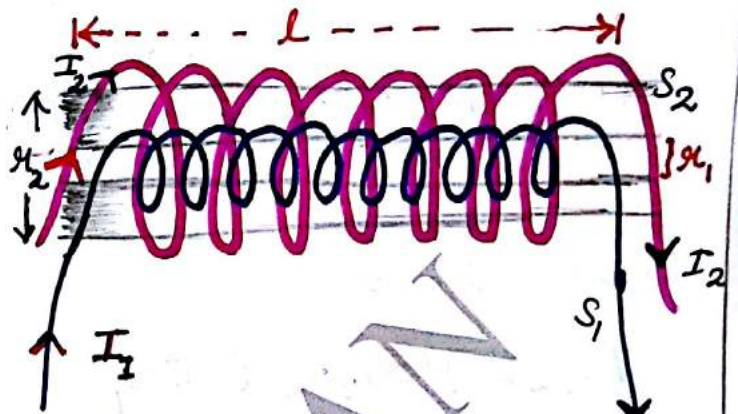
$$W = L \left[ \frac{I^2}{2} \right]_0^I$$

$$W = \frac{1}{2} L I^2$$

energy  $U = \frac{1}{2} L I^2$

This work is stored as energy.

## Mutual Inductance of a pair of coil of different radii



consider two co-axial solenoids  $S_1$  and  $S_2$  of radii  $r_1$  &  $r_2$  let  $I_1$  and  $I_2$  be the currents flowing through  $S_1$  and  $S_2$  respectively. let ' $L$ ' be the length of the solenoid.

let  $n_1$  be the no of turns per unit length of  $S_1$  and  $n_2$  be the no. of turns per unit length of  $S_2$ .

The magnetic flux linked with  $S_1$  due to current flowing through  $S_2$ .

$$\phi_{12} = M_{12} I_2 \quad \dots \text{--- } (1)$$

but we have  $\phi_{12} = B_2 A_1$

$$\phi_{12} = (\mu_0 n_2 I_2) (\pi r_1^2)$$



for  $(n_1 l)$  turns

$$\Phi_{12} = (\mu_0 n_2 I_2) (\pi r_1^2) (n_1 l)$$

$$\Phi_{12} = (\mu_0 n_1 n_2 l \pi r_1^2) I_2 \quad \dots \quad (2)$$

from ① & ②

$$M_{12} = \mu_0 n_1 n_2 l \pi r_1^2$$

\* Now magnetic flux linked with  $S_2$  due to current flowing through  $S_1$

$$\Phi_{21} = M_{21} I_1 \quad \dots \quad (3)$$

but  $\Phi_{21} = B_1 A_1$  [since magnetic flux due to  $I_1$  in  $S_1$  is confined within  $S_1$ ]

$\therefore$  for  $n_2 l$  turns

$$\Phi_{21} = (\mu_0 n_1 I_1) (\pi r_1^2) (n_2 l)$$

$$\Phi_{21} = (\mu_0 n_1 n_2 \pi r_1^2) I_1 \quad \dots \quad (4)$$

from ③ & ④

$$M_{21} = \mu_0 n_1 n_2 l \pi r_1^2$$

$$M_{12} = M_{21}$$



RAHMAN



# \*\* AC Generator. Imp

[CBSE - 2008, 07, 06, 03, 06, 05, 04, D-2010  
F-2012, 2011 (AI)]

A dynamo or generator is a device which converts **mechanical energy** into **electrical energy**.

## Principle.

It works on the principle of **electromagnetic Induction**. i.e., emf is induced when magnetic flux linked with a coil changes.

## Construction.

It consists of four main parts.

### (i) Armature.

It consists of rectangular coil ABCD having large no of turns of insulated copper wire wound on a soft iron cylindrical core.

### (ii) Field magnet.

\* It is a permanent magnet of the horse shoe shape is a small dynamo.

\* In large or high power dynamo electromagnet is used.

### (iii) slip rings ( $S_1$ and $S_2$ )

Two hollow rings attached at the ends of armature. slip rings are insulated brass rings.

### (iv) Brushes ( $B_1, B_2$ )

carbon brushes attached with  $S_1$  and  $S_2$ , to connect with external circuits.

## Source of energy.

The armature coil is rotated about its axis with the help of turbine or any other device connected to it. It is rotational K.E of the turbine which is ultimately converted into electrical energy by the ac generator.

## Working

### First half rotation

- \* plane of coil  $\perp$  to **B**
- \* **AB** front **CD** back



\* coil rotates in **anti clock wise** direction (or **clock wise**)

\* **AB** moves inward and **CD** moves outward.

\* Apply **flemings Right hand rule**.

\* current induced in **AB** from **A to B** and in **CD** from **C to D**

\* In external circuit current flows from **B<sub>2</sub> to B<sub>1</sub>**

second half rotation

\* **AB** is back and **CD** is front. **AB** moves outwards and **CD** moves inwards.

\* The current induced in **AB** is from **B to A** and in **CD** is from **D to C**.

\* Through external circuit current flows from **B<sub>1</sub> to B<sub>2</sub>**

\* This is repeated. Induced current in the external circuit changes direction after every half rotation of the coil. Hence the current

induced is alternating in nature.

Expression for Induced emf.

**N** → No of turns in the coil

**A** → face area of each turn

**B** → magnitude of magnetic field.

**θ** → angle which normal to the coil makes with the field **B** at any instant 't'.

**ω** → angular velocity with which the coil rotates

magnetic

flux

$$\phi = NBA \cos \theta$$

$$\phi = NBA \cos \omega t \quad \text{--- (1)}$$

by Faradays rule induced

emf  $E = -\frac{d\phi}{dt} \quad \text{--- (2)}$

in (2)  $E = -\frac{d(NBA \cos \omega t)}{dt}$

$$E = -NBA [-\sin \omega t] \omega$$

$$E = NBA \sin \omega t \cdot \omega$$

$$E = NBA \omega \cdot \sin \omega t$$

$$E = E_0 \sin \omega t$$

$$I = \frac{E}{R} = \frac{E_0 \sin \omega t}{R}$$

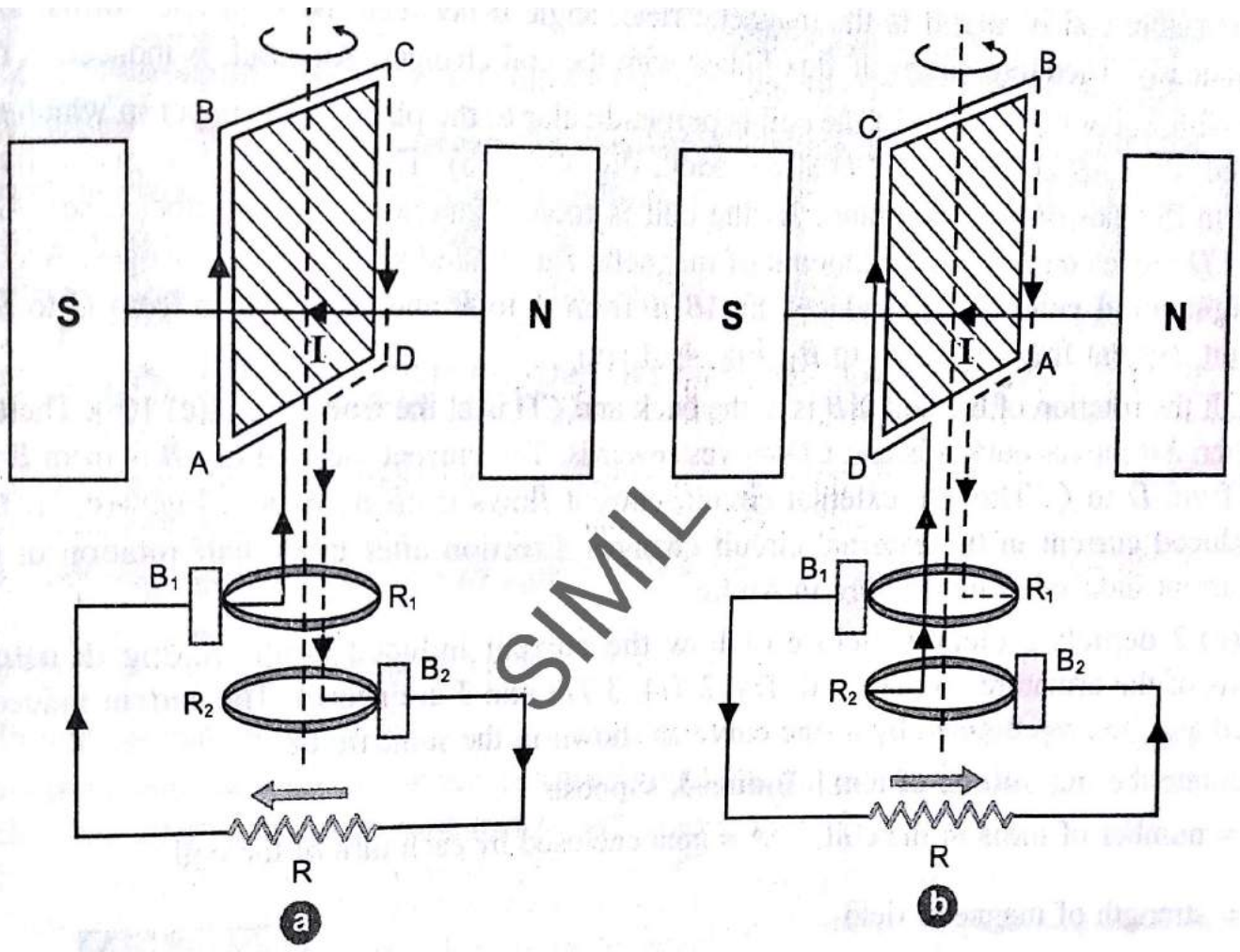
$$I = I_0 \sin \omega t$$

both **E & V** vary with time.

$$E_0 = NBA \omega \times 1$$
$$\sin \omega t = 1$$

$$\frac{E_0}{R} = I_0$$





SIMIL



**Stage 1**  
The plane of the armature is perpendicular to the magnetic field ( $\theta = 0^\circ$ )

**Stage 2**  
When the armature rotates through  $90^\circ$ , the plane of the armature is parallel to magnetic field ( $\theta = 90^\circ$ )

**Stage 3**  
 $\theta = 180^\circ$

**Stage 4**  
 $\theta = 270^\circ$

**Stage 5**  
 $\theta = 360^\circ$

